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### **KMT - Kraus Messtechnik GmbH**

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# TEL1-PCM-HS-BATT User Manual

Digital <u>High Data Rate</u> Telemetry System for Strain Gage and ICP Applications on Rotating Shafts

"Gain and Auto Zero setting direct from Receiver Side!"



- Easy to assemble and operate
- For strain gages or IPC sensors
- Strain gage sensors (>350 Ohm)
- Full- and half bridge configuration
- Excitation fixed 4 Volt DC
- Auto-Zero adjustment Setting receiver side
- Gain: 250-8000 Setting receiver side
- External shunt calibration

- ICP current 4mA, Gain selectable to: 2-4-8-16
- Digital transmission realized inductively
- Distance up to 50mm
- No influence through radio frequency
- Many systems can operated at the same time
- Signal bandwidth 0...50kHz (Scanning rate 104kHz)
- Output +/-10V and digital for interface (Option)
- System accuracy <0.2%</p>

#### **General Description**

The TEL1-PCM-HS-BATT single-channel high data rate telemetry system offers the easiest handling for the wireless transmission of strain gage signals from rotating shafts. The encoder 62x27x13mm with a weight of 30g. The transmitter (encoder) part is simply mounted on the rotating shaft with a special fiber reinforced tape.

Powering of the transmission part is via battery 6-9V or optional inductive power supply. The digital data transfer between transmitter and receiver is realized inductively.

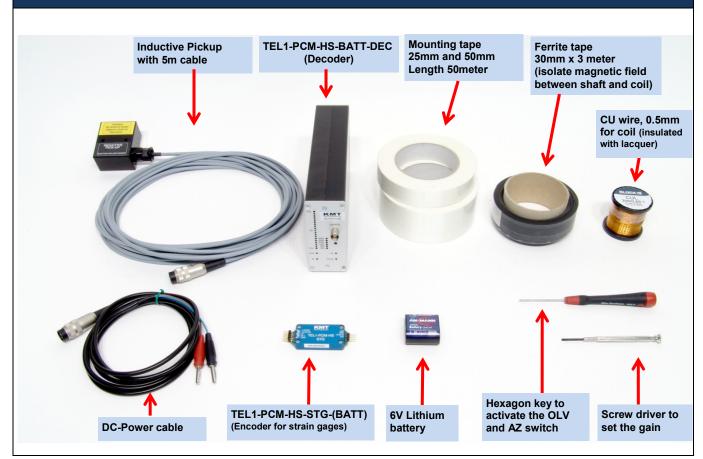
#### **Functional Description**

The TEL1-PCM-HS-BATT transmitter provides a pulse code modulated signal (PCM) to an induction winding around the *shaft* (max. diameter 500mm, other on request!). The magnetic field of this winding enables the inductive transmission of the signal to the pickup coil. From there the signal is transferred by cable (5 m) to the receiver. The maximum distance between the transmitter coil and the pickup is 50mm. (with standard head)

The receiver unit offers a BNC connector at the front panel with analog outputs  $\pm$  10 V and a optional a digital output for PCM interface ECIA100 (for notebooks) or IF16 (PCI Desktop). An LED bar indicator shows the actual level and a successful Auto Zero calibration. Overload is indicated by the last LED's in pos. or neg. direction of the bar graph. These OVL-LED's operate in peak-hold mode and are reset by pressing the overload switch.

Strain gage sensors (>350 Ohm) in full- and half- bridge configuration can be directly connected to the transmitter. The excitation is fixed to 4 Volt DC and the gain is set by the gain switch on the receiver side. An auto-zero (AZ) adjustment is executed by pressing the AZ button on the front side of the receiver. The successful AZ operation is indicated by a yellow LED in the middle of the LED bar indicator. When the AZ completes the LED continuously illuminates. A continued flashing of the yellow LED indicates some error in the AZ electronics. In this case please contact the support of KMT. Additional to the AZ you have the possibility to calibrate the bridge by external shunt. (+ and -). The AZ setting is stored in a Flash-RAM and thus is not lost during power-off. Use only shielded sensor cable.

#### **TEL1-PCM-HS-BATT set contains:**



#### **Technical Data - rotating part**



Strain gage: Full and 1/2 bridge >350 Ohm,

Excitation: 4 VDC (fixed)

Gain: 250; 500; 1000; 2000; 4000; 8000 (selectable from receiver side)



Shunt Cal: Via external resistor for positive and negative calibration

AZ: Auto Zero calibration (selectable from receiver side)

Analog signal bandwidth: 0 - 50 kHz (-3 dB)

Scanning rate 104 kHz

Operating temperature: - 10 to + 80 °C

Dimensions: 62 x 27 x 13mm (without connectors)

Weight: each module 30 grams Static acceleration: up to 3000g

Powering: Battery 6-9V, Power consumption 70mA at 6V

Optional additional inductive powering



For all ICP sensors Curren: 4mA (fixed)

Gain: 1; 2; 4; 8; 16; 32 (selectable from receiver side)





Scanning rate 104 kHz

Operating temperature: - 10 to + 80 °C

Dimensions: 62 x 27 x 13mm (without connectors)

Weight: each module 30 grams Static acceleration: up to 3000g

Powering: Battery 6-9V, current consumption 80mA at 6V

Optional additional inductive powering





#### **Technical Data - static part**





# Front Rear DC POWER CABLE BLACK BLACK RED TUCHEL\_7\_MALE +POWER

#### TEL1-PCM-HS-BATT-DEC

#### Front side:

Analogue output: +/-10V via BNC

Digital output for PCM Interface IF16 (ECIA100) OPTION

Gain setting : via screw switch Auto Zero setting: via micro switch

Overload LED's (Red ON) reset: via micro switch

Green LED's: Bargraph +/-

Autozero LED:

Yellow ON- successful AZ Yellow OFF- not successful AZ

if flashing, call support of KMT, error in EPROM

Green LED's: Bargraph +/-

SL LED: Red ON = if error of data transmitting SL LED: Red Flashing = if distance to far Power ON LED: Red ON = if power switch on

Rear side:

Output to Powerhead: via 5pol. Tuchel Fuse LED: Flashing if fuse is defect

Powering: 10-30V DC, Input via 7pol. Tuchel

Switch: ON/OFF

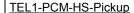
Operating temperature: - 10 to +70 °C

Dimensions: 200 x 105 x 44 (without connectors!)

Weight 950 grams

Static acceleration: up to 200g

System accuracy (without sensor): +/- 0.2 %





code

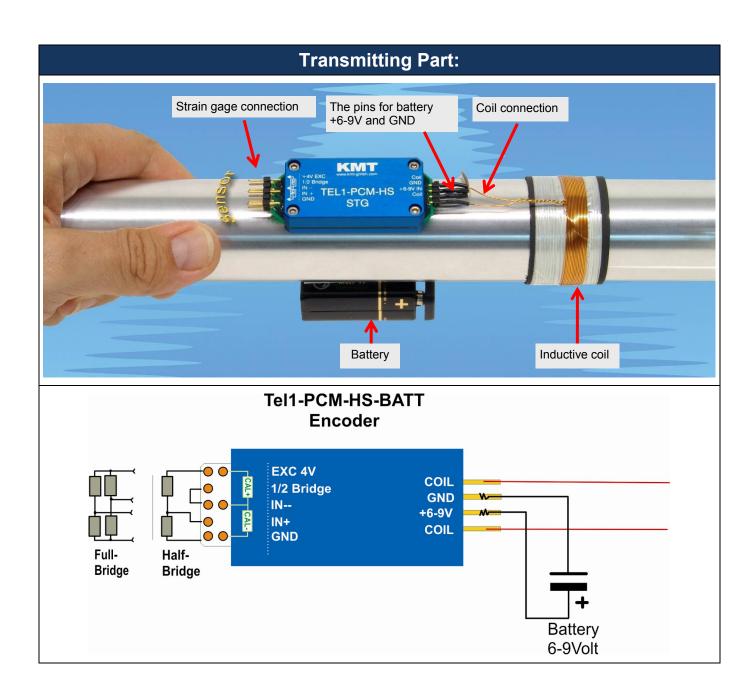
Distance between the transmitter coil and the pickup is 50mm Output to TEL1-PCM-HS-BATT Decoder via 5pol. Tuchel plug incl.

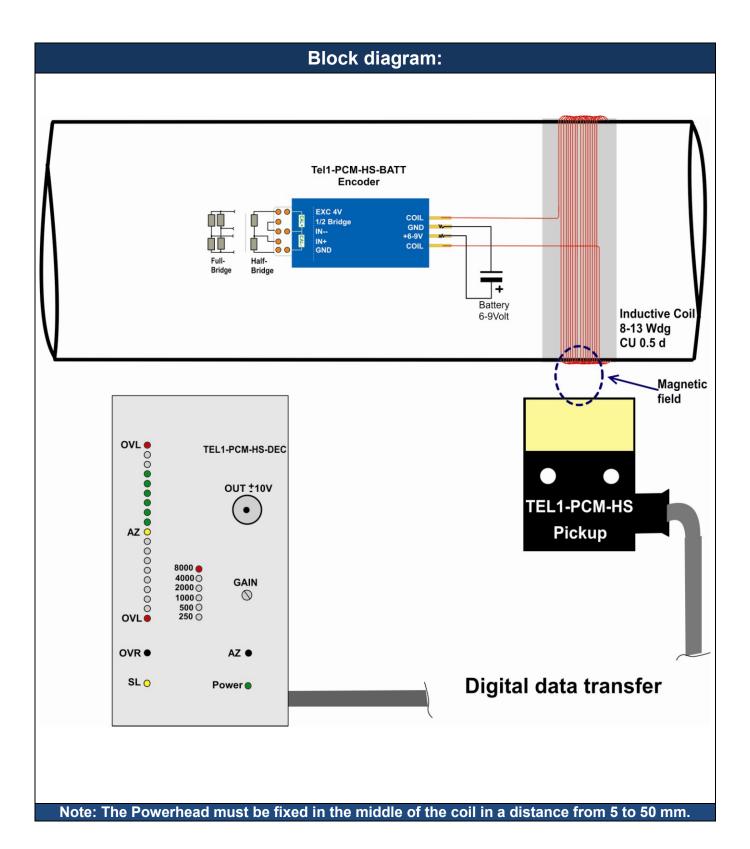
5m cable. Cable length standard 5m, optional 20m

Operating temperature: - 10 to +80 °C Dimensions: 45x60x25mm (without cable) Weight: 400 grams (with 5m cable!)

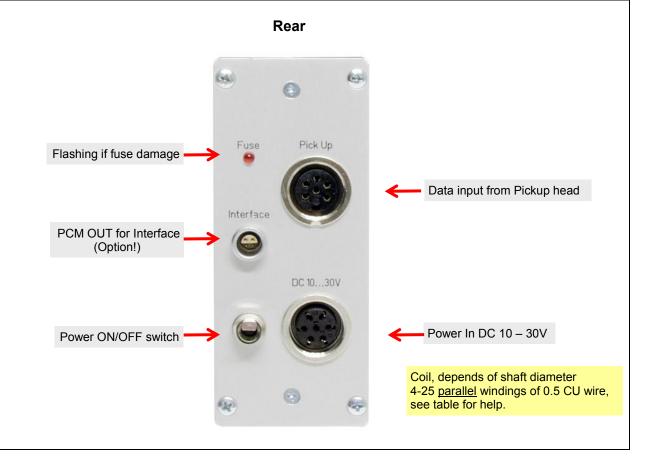
Housing: splash-water resistant IP65 (except connector).

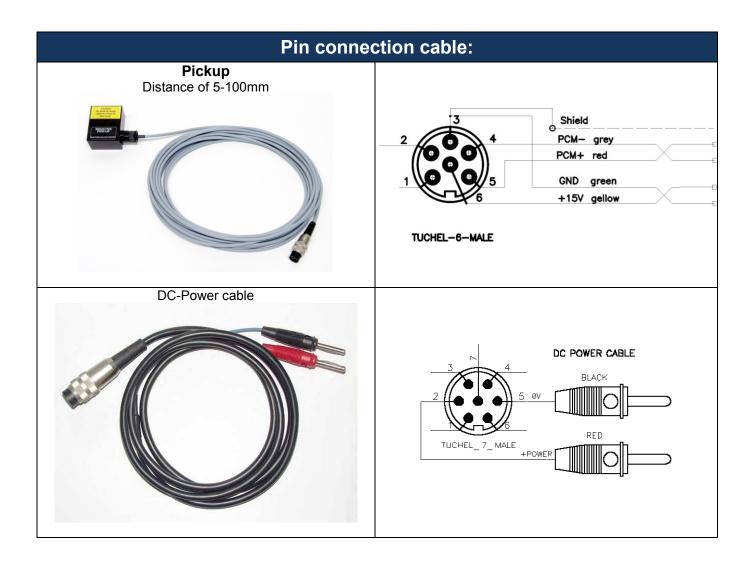






#### **Receiving Part: Front** Positive Baragraph LED With overload indicator TEL1-PCM-HS DEC Out ±10V Auto Zero LED Analog output +/-10V ON = successful OFF = Not successful 8000 4000 2000 Gain Gain switch Negative Baragraph LED 1000 500 250 With overload indicator OVL Reset button of AZ button OVR • AZ • overload indicator Error data transmission LED ON = Power On LED SL • Power ( Battery voltage lower 6V LED Flashing =















around the shaft.

We recommend add. use a steel hose clamp for final fixing!!

10 )



steel hose clamps

#### Caution:

Fix TEL1-PCM-HS-STG-BATT module with at least 10 layers (width 50mm) of the special mounting tape around the shaft. Depending on the shafts RPM and diameter particular attention needs to be paid to the safe mounting of the components.

The manufacturer doesn't accept liability for damages, which results from insufficient attachment of the individual components.

The tape is only for test purposes, in order to test the electrical function of the units in the idle state of the shaft.

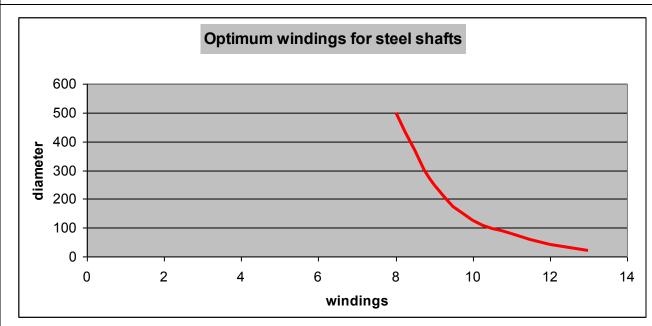
During the rotation test appropriate safety precautions should be taken.

The entire installation may be used only by authorized persons. By using tape for the attachment, it has to be used in the direction of rotation of the shaft and the end has to be secured. Only non-elastic tapes with high tensile strength should be used for pre-fixing. Additionally, use a steel hose clamp for final fixing!! The individual components are to be distributed in such a way on the shaft that imbalances are avoided.

#### Find the correct amount of windings

The number of windings depends on several factors. The most important influential factors are the diameter, the materiel of the shaft and the environment around the shaft. The table standing below will help you to find the right number windings for steel shafts. The table below is a help to <a href="estimate">estimate</a> the number of windings fast. To optimize your results you can try one winding more or less.





Windings	Diameter (mm)
8	600
8	500
9	250
10	125
11	80
12	40
13	20

## Kraus Messtechnik GmbH



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#### Konformitätserklärung

Declaration of Conformity Declaration de Conformité

Wir KMT - Kraus Messtechnik GmbH

We Nous

Anschrift Gewerbering 9, D-83624 Otterfing, Germany

Address Adress

erklären in alleiniger Verantwortung, daß das Produkt declare under our sole responsibility, that the product declarons sous notre seule responsibilité, que le produit

Bezeichnung Messdatenübertragungssystem

Name Nom

Typ, Modell, Artikel-Nr., Größe Type, Model, Article No., Taille Type, Modèle, Mo.d'Article, Taille **TEL1-PCM-HS-BATT** 

mit den Anforderungen der Normen und Richtlinien fulfills the requirements of the standard and regulations of the Directive satisfait aux exigences des normes et directives

108/2004/EG Elektromagnetische Verträglichkeit EMV / EMC

DIN EN 61000-6-3 Ausgabe 2002-8 Elektromagnetische Verträglichkeit EMV Teil 6-3 Fachgrundnorm Störaussendung

DIN EN 61000-6-1 Ausgabe 2002-8 Elektromagnetische Verträglichkeit EMV Teil 6-1 Fachgrundnorm Störfestigkeit

und den angezogenen Prüfberichten übereinstimmt und damit den Bestimmungen entspricht. and the taken test reports und therefore corresponds to the regulations of the Directive et les rapports d'essais notifiés et, ainsi, correspond aux règlement de la Directive.

Otterfing, 27.04.2006 Martin Kraus

Al Ham

Name und Unterschrift des Befugten Name and Signature of authorized person Nom et signature de la personne autorisée

Lieu et date d'établissement

Place and Date of Issua

Version 2009-04

Ort und Datum der Ausstellung

Technical Data are subject to change without notice!

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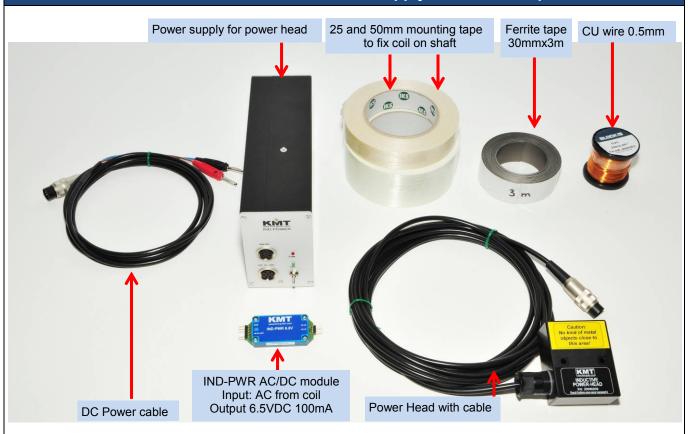
# **Inductive power supply**

# Assembling instructions for TEL1-PCM-HS-BATT

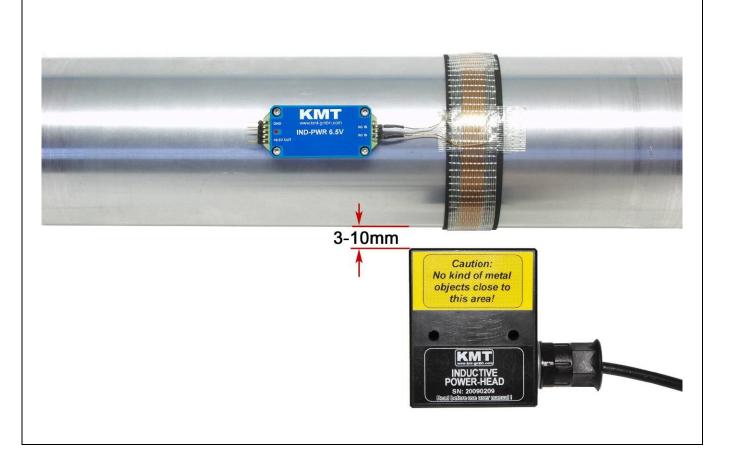


# Inductive power supply set

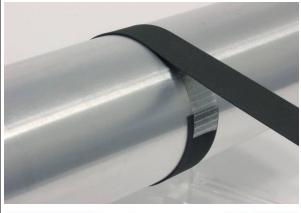
#### Picture shows standard Inductive Power Supply for diameter up to 300mm



#### **Mounted on shaft**



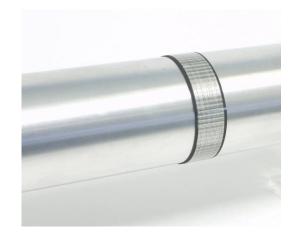
#### Installation of coil for inductive powering on shaft



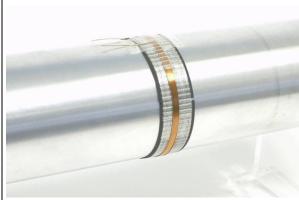


Attach for electromagnetic insulation "Ferrite Tape"

- 2 x layers Ferrite-Tape around the shaft
- Fixed with 2 layers mounting tape







Wind the 0.5 mm enameled copper wire around the shaft:

- 4-25 windings for 500-20mm diameter

Other diameter on request!

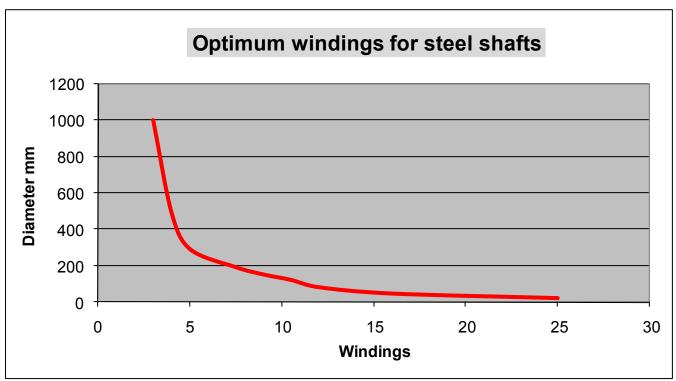
<u>Note:</u> "The inductive load of the IND-PWR AC/DC module and the capacitor in the Power Head must be in resonance to get the optimal transmission. The inductive load of the shaft depends of diameters, material and number of windings."

To find the optimal transmission try one winding more ore less. The LED on the Inductive Power module will help to find the best configuration. The distance between powerhead and the coil is 3-10mm.

Control the output voltage and move the powerhead in the max distance to the coil.

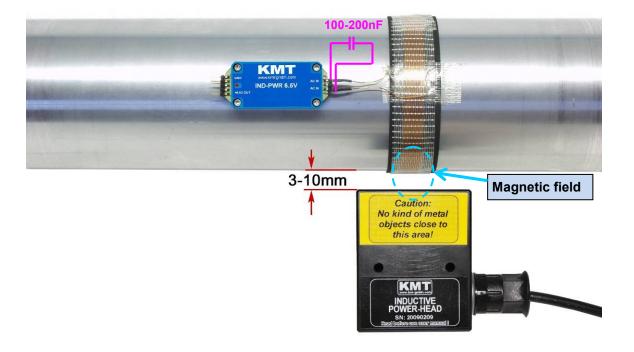
The minimum Output voltage must be 6,5 V!

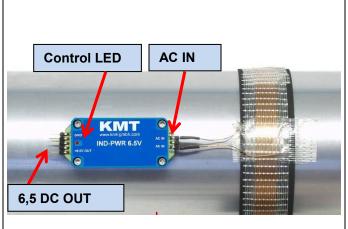
Fix all with 2-3 layers around the coil with mounting tape.



Diameter (mm)	Windings	Fine adjustment capacitor parallel to coil
1000	4-5	100-200nF (Type MKT or MKS 250V)
490	4-5	100-200nF (Type MKT or MKS 250V)
290	5	100-200nF (Type MKT or MKS 250V)
190	7	
150	9	
120	10	
80	12	
45	16	
20	25	





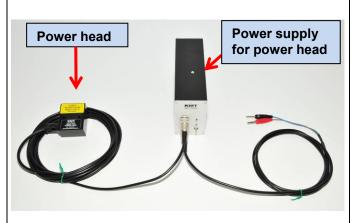


The pins "AC IN" are the AC power input from the coil. On the pins "+6.5" and "GND" you get a stabilized output voltage of 6.5V DC. The control LED will lights up, as soon as the power head is switched on and at the right position - close enough to the coil on the shaft. The max. load current on the DC output is 100mA. The AC/DC converter will use instead battery pack!

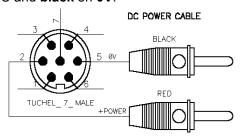


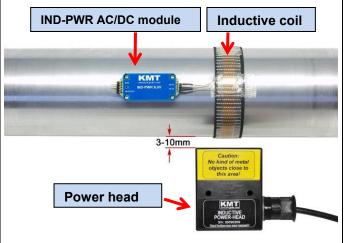
Never use any battery together with the IndPwr!

#### Installation of the power head for inductive powering



Connect the power head on the "AC Out" socket of the power box and then the DC power cable on the "DC In 10-30V" socket. The two banana plugs have to be connected to a DC power source with red on +10-30V DC and **black** on **0V**.





You should mount the power head at a fixed location that it's as free as possible from vibration influences.

The center of the coil should be in the same horizontal position as the center of the power head. The distance is optimal in the range between 3 and 10mm. (depends of shaft and <u>current consumption</u>)

If the red LED of the AC/DC converter lights up, the position of the power head is OK.

#### Fixing of IND-PWR AC/DC module and TEL1-PCM-HS-BATT

Fix all modules with at least 10 layers of the special mounting tape around the shaft.

According to the shafts RPM and diameter it's particularly paid attention to safe mounting of the components.

Add. use hose clamps for final fixing!!

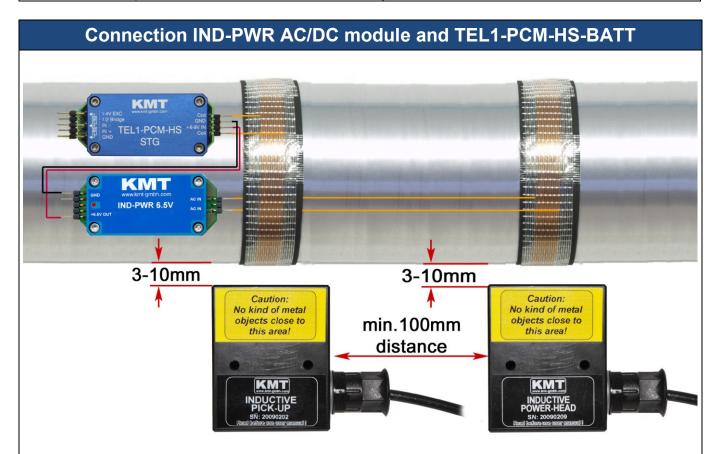




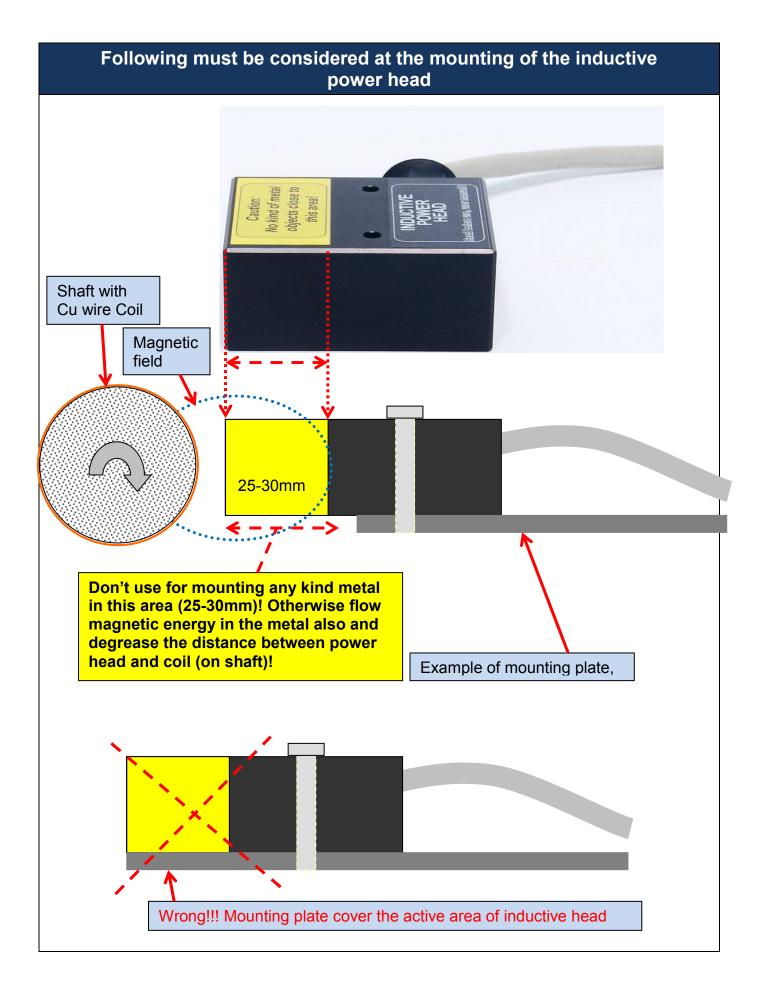
The manufacturer doesn't accept liability for damages, which results from not sufficiently attachment of the individual components. The provided cable harness and the tape are only for test purposes, in order to test the electrical function of the units in the idle state of the shaft.

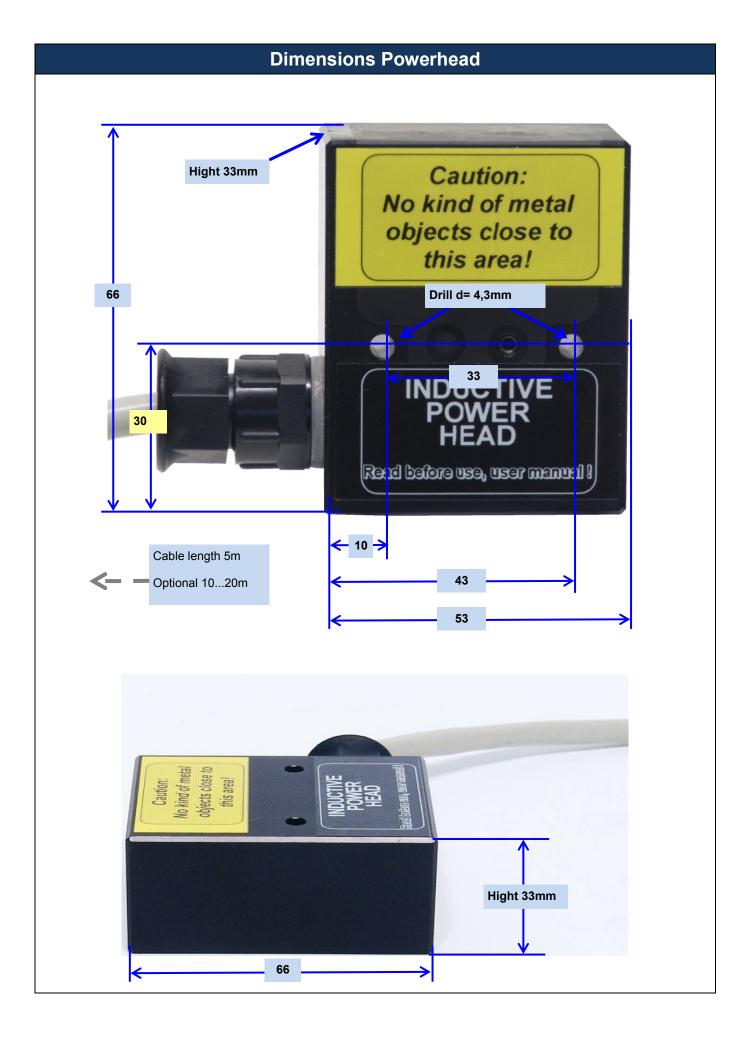
During the rotation test appropriate safety tools are to be attached.

The entire installation may be used only by authorized persons. By using tape for the attachment, it has to be used in the direction of rotation of the shaft and the end has to be secured against removing. Only <u>non-elastic</u> tapes with high tensile strength have to be used <u>for pre-fixing</u>. Add. use hose clamps for final fixing!! The individual components are to be distributed in such a way on the shaft that imbalances will avoid.



To avoid transmitting error, the **mounting distance** between **Inductive Power Head** and **Inductive Pickup Head** must be at least **100mm**.





#### **Attention**

- Use only shielded sensor cable
- When used on rotating shafts, all connections must be soldered.
- Mounting of the modules on a shaft must be first fixed with mounting tape (only for prefixing) and then with a <a href="https://doi.org/10.2016/journal.org/">https://doi.org/10.2016/journal.org/</a>



#### **Safety Notes for Inductive Powering**

- The device should only applied by instructed personnel.
- The power head emits strong magnetic radiation at 60 kHz to a distance of 20 cm. Therefore persons with cardiac pacemakers should not work with this device!
- Magnetic data storage media should be kept in a distance of at least 3m from the power head to avoid data loss. The same is valid for electromagnetic sensitive parts, devices and systems.
- Do not place the power head in the switched-on state on metallic objects, because this
  results in eddy currents, which could overload the device and strongly heat up small
  objects. In addition, the probe could be destroyed!
- No metallic objects, other than the disc-type coil, should be located in the air gap of the power head. The same applies to metallic parts within a radius of up to 15–20 mm in all directions.
- Do not use damaged or faulty cables!
- Never touch in the area between shaft and inductive head, the rotating shaft itself or rotor electronic contacts during operation!
- This is a "Class A" system suitable for operation in a laboratory or industrial environment.
  The system can cause electromagnetic interference when used in residential areas or
  environments. In this case the operator is responsible for establishing protective
  procedures.

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21

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