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up to 10,000 Nm 1 Channel

## F2i S

## Torquemeter

with integrated evaluation unit

#### Description

The new F2i S torque measurement system represents a further development of the new generation with integrated evaluation unit. With the exception of a 24VDC power supply no external components are required for operation.

A high end temperature compensation guarantees a very good stability and repeatability of the output signals. The standard model is equipped with a one track speed measurement system. The maximum allowable speed is 16,000 rpm.



### Significant technical data

- Bearingless torque flange with IR-signal transmission
- Evaluation unit integrated in stator
- High overload capability
- Active temperature compensation to reduce temperature effect on zero balance
- Accuracy 0.1 (Option 0.05)
- Gear tooth speed encoder 60 ppr
- Magnetic speed encoder 1,024 ppr (Option)
- Compact design
- Fits to cardan shaft types 228 and 587
- Transmission of charcteristic values
- Maximum speed 16,000 rpm
- Any torque range up to 10,000 Nm available



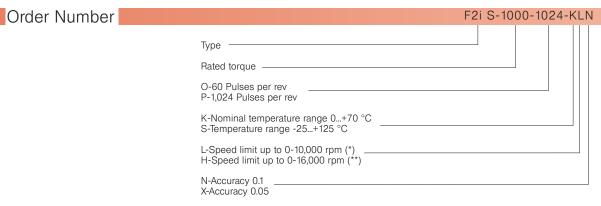
# GESELLSCHAFT FÜR INDUSTRIEFORSCHUNG MBH

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| Nm         | <u>≤</u> 10,000                  |
|------------|----------------------------------|
| Nm         | 5T <sub>r</sub>                  |
|            |                                  |
| % F.S.     | <±0.1                            |
| % F.S./10K | <±0.1                            |
| °C         | 0+70                             |
| rpm        | 16,000                           |
|            | Nm<br>% F.S.<br>% F.S./10K<br>°C |

## Technical Data Torquemeter Type F2i S

| TORQUEMETER  |  |   |
|--|--|---|
| Rated torque nominal T <sub>r</sub>  | Nm   | ≤10,000   |
| Torque limit of torque shaft related to T <sub>r</sub>   | Nm   | >5T <sub>r</sub>  |
| Maximum speed  | rpm  | 16,000  |
| Nonlinearity and hysteresis related to T <sub>r</sub>  | %  | <±0.1   |
| Temperature effect on zero per 10K related to T <sub>r</sub>   | %  | <±0.1   |
| Nominal temperature range  | °C   | 0+70  |
| Operating temperature range  | °C   | -10+80  |
| OUTPUT SPECIFICATION TORQUE  |  |   |
| Frequency output   | kHz  | 60 ± 20   |
| Dynamic response up to   | kHz  | 2   |
| Analog output voltage  | V DC   | 010   |
| Analog output current  | mA   | 020 / 420   |
| Conversion rate / resolution   | MV/s   | 1,000 with 16bit  |
| Shunt calibration  | -  | approx. 30% of T <sub>r</sub>   |
| OUTPUT SPECIFICATION SPEED   |  |   |
| Pulses per rev (gear tooth, 1 track)   | ppr  | 60  |
| Output signal (RS422) frequency  | -  | 1 track   |
| Analog output voltage  | V DC   | 010   |
| Conversion rate / resolution   | MV/s   | 1,000 with 16bit  |
|  |  |   |
|  | rpm  | >0  |
| Required speed   |  |   |
| Required speed  ADDITIONAL INTERFACES / FEATURES   |  |   |
| ADDITIONAL INTERFACES / FEATURES Serial interface RS232 CAN Bus  | rpm  | >0  |
| Required speed  ADDITIONAL INTERFACES / FEATURES  Serial interface RS232  CAN Bus  | rpm<br>Baud  | >0<br>19,200<br>CAN2B up to 1 MBit  |
| Required speed  ADDITIONAL INTERFACES / FEATURES  Serial interface RS232  CAN Bus  Status output   | rpm<br>Baud  | >0  |
| Required speed  ADDITIONAL INTERFACES / FEATURES  Serial interface RS232  CAN Bus  Status output   | rpm<br>Baud  | >0<br>19,200<br>CAN2B up to 1 MBit  |
| ADDITIONAL INTERFACES / FEATURES Serial interface RS232 CAN Bus Status output Remote via additional control line   | rpm<br>Baud  | >0<br>19,200<br>CAN2B up to 1 MBit  |
| ADDITIONAL INTERFACES / FEATURES Serial interface RS232 CAN Bus Status output Remote via additional control line   | rpm<br>Baud  | >0<br>19,200<br>CAN2B up to 1 MBit  |
| ADDITIONAL INTERFACES / FEATURES Serial interface RS232 CAN Bus Status output Remote via additional control line  MECHANICAL DATA Weight (rotor) at 10,000 Nm  | rpm<br>Baud<br>additional contr                            | >0  19,200  CAN2B up to 1 MBit ol line, assignable with status signal   |
| ADDITIONAL INTERFACES / FEATURES  Serial interface RS232  CAN Bus  Status output  Remote via additional control line  MECHANICAL DATA  Weight (rotor) at 10,000 Nm  Inertia (rotor) at 10,000 Nm   | rpm  Baud  additional contr                                | >0  19,200  CAN2B up to 1 MBit ol line, assignable with status signal approx. 14  |
| ADDITIONAL INTERFACES / FEATURES  Serial interface RS232  CAN Bus  Status output  Remote via additional control line  MECHANICAL DATA  Weight (rotor) at 10,000 Nm  Inertia (rotor) at 10,000 Nm  Twist angle at 10,000 Nm   | rpm  Baud  additional contr  kg  gm²                       | >0  19,200  CAN2B up to 1 MBit ol line, assignable with status signal  approx. 14 approx. 87.5                          |
| ADDITIONAL INTERFACES / FEATURES  Serial interface RS232  CAN Bus  Status output  Remote via additional control line  MECHANICAL DATA  Weight (rotor) at 10,000 Nm  Inertia (rotor) at 10,000 Nm  Twist angle at 10,000 Nm  Torsional stiffness  | rpm  Baud  additional contr  kg gm² grad kNm/rad           | >0  19,200 CAN2B up to 1 MBit ol line, assignable with status signal  approx. 14 approx. 87.5 0.05                      |
| Required speed  ADDITIONAL INTERFACES / FEATURES  Serial interface RS232   | rpm  Baud  additional contr  kg  gm²  grad                 | >0  19,200 CAN2B up to 1 MBit ol line, assignable with status signal  approx. 14 approx. 87.5 0.05 2,298                |
| Required speed  ADDITIONAL INTERFACES / FEATURES  Serial interface RS232  CAN Bus  Status output  Remote via additional control line  MECHANICAL DATA  Weight (rotor) at 10,000 Nm  Inertia (rotor) at 10,000 Nm  Twist angle at 10,000 Nm  Torsional stiffness  Coupling mass (typ.)  Fits to cardan shafts | rpm  Baud  additional contr  kg  gm²  grad  kNm/rad  kg    | 19,200 CAN2B up to 1 MBit ol line, assignable with status signal approx. 14 approx. 87.5 0.05 2,298 20                  |
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(\*)=with 1,024 ppr speed encoder (\*\*)=with 60 ppr gear tooth

