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F3i S

up to 50.000 Nm
1 Channel

Torquemeter

with integrated evaluation unit

Description

The new F3i S torque measurement system represents a further development of the GIF torque-meter model family. The appropriate evaluation unit is now integrated in the stator. With the exception of a 24VDC power supply no external components are required for operation. A high end temperature compensation guarantees a very good stability and repeatability of the output signals. The customer interface is very flexible, due to the availibility of multiple outputs.



Significant technical data

- Bearingless torque flange with IR-signal transmission
- Evaluation unit integrated in stator
- High overload capability
- Active temperature compensation to reduce temperature effect on zero balance
- Accuracy 0.1
- Optical speed encoder 1000 ppr (Option)
- Fits to cardan shaft types 228 and 587
- Compact design
- Transmission of characteristic values



GESELLSCHAFT FÜR INDUSTRIEFORSCHUNG MBH

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Rated torque T _r	Nm	≤50,000
Overload capability torsional shaft	Nm	5T _r
Accuracy including hysteresis		
and nonlinearity	% F.S.	<±0.1
Temperature effect on zero	% F.S./10K	<±0.1
Operating temperature range	°C	0+70
Maximum speed	rpm	5,000

Technical Data Torquemeter Type F3i S

Rated torque nominal T ₁	TORQUEMETER		
Maximum speed rpm	Rated torque nominal T _r	Nm	<u>≤</u> 50,000
Nonlinearity and hysteresis related to T,	Torque limit of torque shaft related to T _r	Nm	>5T _r
Temperature effect on zero per 10K related to T,	Maximum speed	rpm	5,000
Nominal temperature range	Nonlinearity and hysteresis related to T _r	%	<±0.1
Operating temperature range °C -10480 OUTPUT SPECIFICATION TORQUE Frequency output kHz 2 Dynamic response up to kHz 2 Analog output voltage V DC +/-10 Analog output current mA 0.20 / 4.20 Conversion rate / resolution MV/s 1,000 with 16bit Shunt calibration - approx. 30% of T, OUTPUT SPECIFICATION SPEED ADDITIONAL INTERFACES / FEATURES Serial interface RS232 Baud 19,200 CAN Bus CAN2B up to 1 MBit Status output additional control line, assignable with status signal Remote via additional control line MECHANICAL DATA Weight (rotor) at 10,000 Nm grad 10,000 Nm 10,00	Temperature effect on zero per 10K related to T_r	%	<±0.1
OUTPUT SPECIFICATION TORQUE Frequency output kHz 60 ± 20 Dynamic response up to kHz 2 Analog output voltage V DC +/- 10 Analog output current mA 0.20 / 4.20 Conversion rate / resolution MV/s 1,000 with 16bit Shunt calibration - approx. 30% of T _r ADDITIONAL INTERFACES / FEATURES Serial interface RS232 Baud 19.200 CAN Bus CAN2B up to 1 MBit Status output additional control line, assignable with status signal Remote via additional control line MECHANICAL DATA MECHANICAL DATA Weight (roto) at 10,000 Nm kg approx. 45 Inertia (roto) at 10,000 Nm grad 0.0048 Torsional stiffness kNm/rad 36,700 Coupling mass (typ.) kg 3500 OPTIONS Nonlinearity and hysteresis related to T, kg < ±0.05 Tomperature effect on zero per 10K related to T, kg < ±0.05 Tomperature effect on zero per 10K related to T, kg < ±0.05	Nominal temperature range	°C	0+70
Frequency output	Operating temperature range	°C	-10+80
Dynamic response up to kHz 2 Analog output voltage V DC +/- 10 Analog output current mA 020 / 420 Conversion rate / resolution MV/s 1,000 with 16bit Shunt calibration - approx. 30% of T _r CUTPUT SPECIFICATION SPEED ADDITIONAL INTERFACES / FEATURES Serial interface RS232 Baud 19,200 CAN Bus CAN2B up to 1 MBit Status output additional control line, assignable with status signal Remote via additional control line MECHANICAL DATA Weight (rotor) at 10,000 Nm kg approx. 45 Inertia (rotor) at 10,000 Nm grad 0.0048 Torsional stiffness kNum/rad 36,700 Coupling mass (typ.) Age 3500 OPTIONS Nonlinearity and hysteresis related to T _r % < 4.0.05 Emperature effect on zero per 10K related to T _r % < 4.0.05	OUTPUT SPECIFICATION TORQUE		
Dynamic response up to kHz 2 Analog output voltage V DC +/- 10 Analog output current mA 020 / 420 Conversion rate / resolution MV/s 1,000 with 16bit Shunt calibration - approx. 30% of T _r CUTPUT SPECIFICATION SPEED ADDITIONAL INTERFACES / FEATURES Serial interface RS232 Baud 19,200 CAN Bus CAN2B up to 1 MBit Status output additional control line, assignable with status signal Remote via additional control line MECHANICAL DATA Weight (rotor) at 10,000 Nm kg approx. 45 Inertia (rotor) at 10,000 Nm grad 0.0048 Torsional stiffness kNum/rad 36,700 Coupling mass (typ.) Age 3500 OPTIONS Nonlinearity and hysteresis related to T _r % < 4.0.05 Emperature effect on zero per 10K related to T _r % < 4.0.05		kHz	60 ± 20
Analog output voltage V DC +/-10 Analog output current mA 0.20 / 4,20 Conversion rate / resolution MV/s 1,000 with 16bit Shunt calibration - approx. 30% of Tr OUTPUT SPECIFICATION SPEED ADDITIONAL INTERFACES / FEATURES Serial interface RS232 Baud 19,200 CAN Bus CAN2B up to 1 MBit Status output additional control line, assignable with status signal Remote via additional control line MECHANICAL DATA Weight (rotor) at 10,000 Nm kg approx. 584 Inertia (rotor) at 10,000 Nm grad 0,0048 Torsional stiffness kn/m/rad 36,700 Coupling mass (typ.) kg 3500 OPTIONS Nonlinearity and hysteresis related to Tr, % < <±0.05 Temperature effect on zero per 10K related to Tr, % < <±0.05 Temperature effect on zero per 10K related to Tr, % < <±0.05		kHz	2
Analog output current mA 020 / 420 Conversion rate / resolution MV/s 1,000 with 16bit Shunt calibration - approx. 30% of T, OUTPUT SPECIFICATION SPEED ADDITIONAL INTERFACES / FEATURES Serial interface RS232 Baud 19,200 CAN Bus CAN2B up to 1 MBit Status output additional control line, assignable with status signal Remote via additional control line MECHANICAL DATA Weight (rotor) at 10,000 Nm kg approx. 584 Twist angle at 10,000 Nm grad 0.0048 Torsional stiffness KNm/rad 36,700 Coupling mass (typ.) kg 3500 OPTIONS Nonlinearity and hysteresis related to T _r % < ±0.05 Temperature effect on zero per 10K related to T _r % < ±0.05 Temperature effect on zero per 10K related to T _r % < ±0.05			
Conversion rate / resolution MV/s 1,000 with 16bit Shunt calibration - approx. 30% of T _r OUTPUT SPECIFICATION SPEED ADDITIONAL INTERFACES / FEATURES Serial interface RS232 Baud 19,200 CAN2B up to 1 MBit Status output additional control line, assignable with status signal Remote via additional control line MECHANICAL DATA Weight (rotor) at 10,000 Nm kg approx. 45 Inertia (rotor) at 10,000 Nm grad 0.0048 Twist angle at 10,000 Nm grad 0.0048 Torsional stiffness kNm/rad 36,700 Coupling mass (typ.) kg 3500 OPTIONS Nonlinearity and hysteresis related to T _r % <±0.05 Temperature effect on zero per 10K related to T _r % <±0.05			
Shunt calibration - approx. 30% of T, OUTPUT SPECIFICATION SPEED ADDITIONAL INTERFACES / FEATURES Serial interface RS232 Baud 19,200 CAN Bus CAN2B up to 1 MBit Status output additional control line, assignable with status signal Remote via additional control line MECHANICAL DATA Weight (rotor) at 10,000 Nm kg approx. 45 Inertia (rotor) at 10,000 Nm grad 0.0048 Twist angle at 10,000 Nm grad 0.0048 Torsional stiffness RNm/rad 36,700 Coupling mass (typ.) kg 3500 OPTIONS Nonlinearity and hysteresis related to T, % < <±0.05 Temperature effect on zero per 10K related to T, % < <±0.05			
OUTPUT SPECIFICATION SPEED ADDITIONAL INTERFACES / FEATURES Serial interface RS232 Baud 19,200 CAN Bus CAN2B up to 1 MBit Status output additional control line, assignable with status signal Remote via additional control line MECHANICAL DATA Weight (rotor) at 10,000 Nm kg approx. 45 Inertia (rotor) at 10,000 Nm grad 0,0048 Torsional stiffness kNm/rad 36,700 Coupling mass (typ.) kg 3500 OPTIONS Nonlinearity and hysteresis related to T _r % < ±0.05 Temperature effect on zero per 10K related to T _r % < ±0.05 Temperature effect on zero per 10K related to T _r % < ±0.05			
Status output additional control line, assignable with status signal Remote via additional control line MECHANICAL DATA Weight (rotor) at 10,000 Nm kg approx. 45 Inertia (rotor) at 10,000 Nm grad approx. 584 Twist angle at 10,000 Nm grad 0.0048 Torsional stiffness kNm/rad 36,700 Coupling mass (typ.) kg 3500 OPTIONS Nonlinearity and hysteresis related to T _r % <±0.05 Temperature effect on zero per 10K related to T _r % <±0.05		Baud	19,200
MECHANICAL DATA Weight (rotor) at 10,000 Nm kg approx. 45 Inertia (rotor) at 10,000 Nm gm² approx. 584 Twist angle at 10,000 Nm grad 0.0048 Torsional stiffness kNm/rad 36,700 Coupling mass (typ.) kg 3500 OPTIONS Nonlinearity and hysteresis related to T _r % <±0.05 Temperature effect on zero per 10K related to T _r % <±0.05	CAN Bus		CAN2B up to 1 MBit
MECHANICAL DATAWeight (rotor) at 10,000 Nmkgapprox. 45Inertia (rotor) at 10,000 Nmgm²approx. 584Twist angle at 10,000 Nmgrad0.0048Torsional stiffnesskNm/rad36,700Coupling mass (typ.)kg3500OPTIONSNonlinearity and hysteresis related to T_r % $<\pm 0.05$ Temperature effect on zero per 10K related to T_r % $<\pm 0.05$		additional contro	ol line, assignable with status signal
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Remote via additional control line		
Inertia (rotor) at 10,000 Nm gm² approx. 584 Twist angle at 10,000 Nm grad 0.0048 Torsional stiffness kNm/rad 36,700 Coupling mass (typ.) kg 3500 OPTIONS Nonlinearity and hysteresis related to T_r % $<\pm0.05$ Temperature effect on zero per 10K related to T_r % $<\pm0.05$	MECHANICAL DATA		
Twist angle at 10,000 Nm grad 0.0048 Torsional stiffness kNm/rad 36,700 Coupling mass (typ.) kg 3500 OPTIONS Nonlinearity and hysteresis related to T_r % $<\pm0.05$ Temperature effect on zero per 10K related to T_r % $<\pm0.05$	Weight (rotor) at 10,000 Nm	kg	approx. 45
$\begin{tabular}{lllllllllllllllllllllllllllllllllll$	Inertia (rotor) at 10,000 Nm	gm²	approx. 584
	Twist angle at 10,000 Nm	grad	0.0048
	Torsional stiffness	kNm/rad	36,700
Nonlinearity and hysteresis related to T_r % $<\pm0.05$ Temperature effect on zero per 10K related to T_r % $<\pm0.05$	Coupling mass (typ.)	kg	3500
Nonlinearity and hysteresis related to T_r % $<\pm0.05$ Temperature effect on zero per 10K related to T_r % $<\pm0.05$	OPTIONS		
Temperature effect on zero per 10K related to T_r % $^{\pm0.05}$		%	<±0.05
	High resolution optical speed encoder with 1,000 ppr (2 tracks)	70	5.00





