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COMPUTER CONTROLLED PAN-TILT UNIT Models PTU-46-17.5 & PTU-46-70



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Technical Specifications

General Features

- Simple to use from any RS-232 terminal or computer
- Fast and accurate camera positioning at low cost
- Precise control of position, speed & acceleration
- · Small form factor
- · Allows on-the-fly position and speed changes
- Self calibration upon reset
- Power consumption can be controlled from host
- ASCII command mode for simplicity, binary commands available for efficient program control
- DC power input from an unregulated source
- Radiation hardened
- CE Mark certified for Europe

Pan-Tilt Performance

	PTU-46-17.5	PTU-46-70
Rated payload	4 lbs (1.81kg)	6 lbs (2.72kg)
Max. unloaded speed (@36VDC)	300°/second	60°/second
Resolution	3.086 arc minutes (0.051428°)	0.771 arc minutes (0.012857°)

Acceleration/Deceleration: Trapezoidal. On-the-fly speed and position changes.

Tilt Range (approx): minimum 31° up and 47° down (78° range) with option of 80° down (111° range)

Pan Range (approx): ±159° (318° range) with option of ±180° (360° range)

Power Requirements

Input Voltage: 11-37VDC unregulated

Power Consumption:

16W continuous peak (full-power mode)
7.5W continuous peak (low-power mode)
1W continuous peak (holding power off mode)

Mechanical

Pan-Tilt Unit:

- **− Weight:** 3 lb.
- **Dimensions:** 3" wide x 5.13" high x 4.25" deep
- Camera mounting: Hole for 1/4-20 screw standard.
 Camera mounting plate removes for easy customizing.
- **Pan-tilt unit mounting:** Bottom or front 1/4-20 mounting

Controller:

- **Weight:** 12 oz.

- **Dimensions:** 3.4" wide x 5.5" long x 2.5" high

Specifications subject to change without notice.

Built-In Connectivity Capabilities

Basic Mode: Host RS-232 port controls single pan-tilt unit Extended Mode: Control of multiple pan-tilt units from one or more host computers. Multidrop RS-485 network using RJ-11.

Host Control

Host: RS-232 (default is 9600 baud, 1 start bit, 8 data bits, 1 stop bit, no parity, no handshaking). DB-9 female connector.

Host modes: Interactive Mode (ASCII command set) and Encoded Mode (binary format for higher bandwidth computer control)

Commands include:

<axis> is T for the tilt axis or P for the pan axis.

Axis Control Commands:

General form: <axis><command><value><dem> [<status>]
Go to position: <axis>P<position><delim> [<status>]

Move power mode:

<axis>M[<hi power> | <reg power> | <lo power>]<delim> [<status>]

Hold (stationary) power mode:

<axis>H[<reg power> | <lo power> | <power off>]<delim> [<status>]

Axis Queries:

General form: <axis><command><delim> <query answer> (Axis Control Commands become queries when the <value> argument is omitted.)

 $\label{eq:Resolution: axis} \textbf{Resolution: } < axis > \textbf{R} < delim > \quad < axis > \textbf{per position} > \\ \textbf{Position bounds: } < axis > \textbf{[N | X]} < delim > \quad < boundary position > \\ \end{cases}$

Unit Commands:

Command menu: ?<delim> <menu>
Await completion: A<delim> <status>
Reset unit: R<delim> [<status>]
Immediate mode: I<delim> [<status>]
 (immediate position command execution)
Slaved mode: S<delim> [<status>]

(position commands execute upon Await Completion command) **Defaults:** D[<save> | <restore> | <factory settings>] <delim> [<status>]

(Saves and restores unit defaults at power up)

Available Options

- International AC/DC Power Supply (model PT-PS-IHPS)
- Weatherized option provides outdoor use (add "W" to PTU model)
- Nodal (gimbal) pan-tilt adaptor
 - Payload can mount at the intersection of the pan and tilt axes
 - Uses include rotating camera at focal point & mirror positioning
- C Programmer's Interface (model PTU-CPI)
- PTU network cabling kits (PTU-NET-SK and PTU-NET-AU)
- · Analog joystick interface



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