## AHRS440

MEMS-BASED AHRS SYSTEM


## Features

- Roll, Pitch, Heading and 9DOF Inertial Outputs
- Accuracy < 0.2 deg
- Output Data Rate > 100 Hz
- High-Range Sensor Options (400 deg/sec and 10g)
- GPS Aiding Input
- Low Power < 3W
- High Reliability, MTBF > 25,000 hours
- Analog Output Option
- Rugged Sealed Enclosure


## Certifications

- DO-160D Environments
- Avionics Systems
- Platform Stabilization


## Applications

- Unmanned Vehicle Control
- Land Vehicle Guidance



## Performance

## AHRS440

| Heading | $\pm 180$ |
| :--- | :--- |
| Range $\left({ }^{\circ}\right)$ | $<1.0$ |
| Accuracy $\boldsymbol{y}^{1,2,3}\left({ }^{\circ}\right)$ | $<0.1$ |
| Resolution $\left({ }^{\circ}\right)$ |  |

## Attitude

| Range: Roll, Pitch $\left({ }^{\circ}\right)$ | $\pm 180, \pm 90$ |
| :--- | :--- |
| Accuracy ${ }^{1,2,3}\left({ }^{\circ}\right)$ | $<0.2$ |
| Resolution $\left({ }^{\circ}\right)$ | $<0.02$ |

## Angular Rate

| Range: Roll, Pitch, Yaw $\left({ }^{\circ} / \mathrm{sec}\right)$ | $\pm 200( \pm 400$ option available $)$ |
| :--- | :--- |
| Bias Stability In-Run ${ }^{2,4}\left({ }^{\circ} / \mathrm{hr}\right)$ | $<10$ |
| Bias Stability Over Temp ${ }^{2}(\% / \mathrm{sec})$ | $<0.02$ |
| Resolution $\left({ }^{\circ} / \mathrm{sec}\right)$ | $<0.02$ |
| Angle Random Walk $\left({ }^{\circ} / \mathrm{Jhr}\right)$ | $<4.5$ |
| Bandwidth $(\mathrm{Hz})$ | 25 |

## Acceleration

| Input Range: X/Y/Z (g) | $\pm 4( \pm 10$ option available) |
| :--- | :--- |
| Bias Stability In-Run ${ }^{2,4}(\mathrm{mg})$ | $<1$ |
| Bias Stability Over Temp ${ }^{2}(\mathrm{mg})$ | $<4$ |
| Resolution $(\mathrm{mg})$ | $<0.5$ |
| Velocity Random Walk $(\mathrm{m} / \mathrm{s} / \sqrt{ } \mathrm{hr})$ | $<1.0$ |
| Bandwidth $(\mathrm{Hz})$ | 25 |

## Specifications

| Environment |  |
| :---: | :---: |
| Operating Temperature ( ${ }^{\circ} \mathrm{C}$ ) | -40 to +71 |
| Non-Operating Temperature ( ${ }^{\circ} \mathrm{C}$ ) | -55 to +85 |
| Enclosure | IP66 Compliant |
| Electrical |  |
| Input Voltage (VDC) | 9 to 42 |
| Power Consumption (W) | < 3 |
| Digital Interface | RS-232 |
| Physical |  |
| Size (in) | $3 \times 3.75 \times 3$ |
| (cm) | $7.62 \times 9.53 \times 7.62$ |
| Weight (lbs) | $<1.3$ |
| (kg) | < 0.58 |
| Connector | DB15, D-sub 15-pin Male |

## Ordering Information

| Model | Description |
| :--- | :--- |
| AHRS440CA-200 | Attitude \& Heading Reference System (Standard) |
| AHRS440CA-400 | Attitude \& Heading Reference System (High Range) |

This product has been developed exclusively for commercial applications. It has not been tested for, and makes no representation or warranty as to conformance with, any military specifications or its suitability for any military application or end-use. Additionally, any use of this product for nuclear chemical or biological weapons, or weapons research, or for any use in missiles, rockets, and/or UAV's of 300 km or greater range, or any othe activity prohibited by the Export Administration Regulations, is expressly prohibited without the written consent and without obtaining appropriate US export license(s) when required by US law. Diversion contrary to U.S. law is prohibited. Specifications are subject to change without notice Notes: ${ }^{1}$ With valid GPS-Aiding input data. ${ }^{2} 1$-sigma value. ${ }^{3}$ During steady level flight. ${ }^{4}$ Constant temperature, Allan Variance Curve.

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## Analog Output Option

ACEINNA offers the NAV-DAC440 analog interface adapter for customers wishing to use the AHRS440 in analog data acquisition systems. The NAV-DAC440 converts the AHRS440 serial digital data to 9-channel BNC analog outputs.

NAV-VIEW 2.0
Configuration \& Display Software


NAV-VIEW 2.0 provides an easy to use graphical interface to display, record and analyze all of the AHRS440 measurement parameters.

## Other Components

Each AHRS440 is shipped with an interface cable, ACEINNA's User's Manual and NAV-VIEW 2.0 configuration and display software.

## Support

For more detailed technical information please refer to the 440-Series User's www.aceinna.com/support

